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Calibration certificate

Pages

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Release date:

26 FEB, 2019

Product code

SR30-D1

Product identification

serial number 3184

Product type Measurand pyranometer

hemispherical solar radiation

Calibration result

Sensitivity

 $S = 10.31 \times 10^{-6} \text{ V/(W/m}^2)$

Calibration uncertainty $\pm 0.10 \times 10^{-6} \text{ V/(W/m}^2)$

the number following the \pm symbol is the expanded uncertainty with a

coverage factor k = 2, and defines an interval estimated to have a

level of confidence of 95 percent

Reference conditions

20 °C, normal incidence solar radiation, horizontal mounting,

irradiance level 1000 W/m²

Measurement process

Metrological characteristic

S in $[V/(W/m^2)]$: sensitivity to irradiance in the 300 to 3000

x 10⁻⁹ m range, with 180° field of view angle, valid for reference

conditions

Calibration method

indoor calibration according to ISO 9847, type IIc

Measurement equipment Hukseflux Solar Radiation Calibration

Metrological traceability

Calibration traceability Calibration hierarchy to WRR (World Radiometric Reference) from WRR through ISO 9846 and ISO 9847 pyranometer type SR20, serial number 5039

Working standard Calibration institute

PMOD World Radiation Center, Davos, Switzerland

Standard sensitivity $14.60 \times 10^{-6} \text{ V/(W/m}^2)$

Evaluation of the uncertainty of the calibration result

Uncertainty calculation

the calibration uncertainty calculated as the square root of the sum of the squares of the calibration uncertainty of the working standard, the uncertainty of the method and the uncertainty due to deviations from

the reference conditions is \pm 1.0 %.

Person performing calibration:

Date:

D.G. Dima

22 FEB, 2019

Person authorising calibration result of product:

Date:

H.E. Brouwer

26 FEB, 2019

Certificate identification: 201902.SR30-D1.3184.01

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Product certificate

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Release date:

26 FEB, 2019

Product code

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Product identification

serial number 3184

Product type

pyranometer

Measurand Classification hemispherical solar radiation

secondary standard (ISO 9060), high quality (WMO-No. 8)

Calibration result

Sensitivity

 $S = 10.31 \times 10^{-6} \text{ V/(W/m}^2)$

Calibration uncertainty

 $\pm 0.10 \times 10^{-6} \text{ V/(W/m}^2)$

the number following the \pm symbol is the expanded uncertainty with a coverage factor k=2, and defines an interval estimated to have a

level of confidence of 95 percent

Product specifications and conformity

1:	ISO 9060 secondary standard	verified
2:	resistance	18.9 Ω
3:	insulation resistance	$> 100 \times 10^6 \Omega$
4:	response time (95 %)	3.2 s
5:	temperature response	verified
6:	directional response	verified
7:	tilt measurement uncertainty	± 1 ° (0 to 90 °)

Table 0.1 connections

PIN	WIRE	
1	Brown	VDC [+]
4	Black	VDC [-]
3	Blue	not connected
2	White	RS-485 B / B' [+]
5	Grey	RS-485 A / A' [-]
	Yellow	shield

Calibration procedure according to ISO 9847. Traceability of calibration is to the WRR (World Radiometric Reference) maintained at the World Radiation Center in Davos, Switzerland.

Please consult the user manual for set up, operation and maintenance instructions, and information on measurement uncertainty during actual use.

Person authorising acceptance and release of product:

Date:

H.E. Brouwer



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Directional response

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Product type

pyranometer

Measurand Classification hemispherical solar radiation

secondary standard (ISO 9060), high quality (WMO-No. 8)

Characterisation result

Directional response

 $\leq \pm 7.6 \text{ W/m}^2$

Measurement process

Characterised parameter

dependence of sensitivity resulting from the direction of irradiance (a

measure of the deviations from an ideal cosine response and its

azimuthal variation)

Measurement functions

 $C_{rel} = S(\theta)/(S(0)\cdot\cos(\theta) - 1)\cdot100 \%$

with C_{rel} the deviation from an ideal cosine response at zenith angle θ in [%], $S(\theta)$ the sensitivity to beam irradiance at zenith angle θ in [V/(W/m²)], S(0) the sensitivity to beam irradiance at normal

incidence, θ the incoming angle from zenith in [°] $C_{abs} = (S(\theta)/(S(0) \cdot cos(\theta) - 1)) \cdot cos(\theta) \cdot 1000$

with C_{abs} the directional response as defined below in [W/m²]

Measurement equipment

Hukseflux Directional Response Characterisation

Conformity assessment

Definition of measurand

The directional response is the error caused by assuming that the

reported sensitivity is valid when measuring from any direction a beam

whose normal incidence is 1000 W/m²

Acceptance interval

ISO 9060 specifies a limit on the directional response for a secondary

standard pyranometer of ± 10 W/m²

Conclusion

Conformity verified

Table 0.2 directional response test result

DIRECTIONAL RESPONSE TEST								
azimuth	zimuth North		East		South		West	
zenith	C _{abs} [W/m ²]	C _{rel} [%]	C _{abs} [W/m ²]	C _{rel} [%]	C _{abs} [W/m ²]	C _{rel} [%]	C _{abs} [W/m²]	C _{rel} [%]
40 °	-1.9	-0.2	+1.5	+0.2	+7.6	+1.0	+4.7	+0.6
60 °	-2.4	-0.5	+0.6	+0.1	+7.3	+1.5	+5.1	+1.0
70 °	-2.7	-0.8	-0.4	-0.1	+5.6	+1.6	+4.3	+1.3
80 °	-2.6	-1.5	-0.2	-0.1	+4.8	+2.8	+3.9	+2.3

Person performing characterisation:

Date:

D.G. Dima



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Temperature response

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Product identification

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Product type

pyranometer

Measurand

hemispherical solar radiation

Classification

secondary standard (ISO 9060), high quality (WMO-No. 8)

Characterisation result

Temperature response Temperature coefficients* $< \pm 0.04 \%$ (-30 to +50 °C) a = -16.3362 x 10⁻⁶ °C⁻²

a = -10.3302 x 10 °C

 $b = 6.7378 \times 10^{-4} \, {}^{\circ}\text{C}^{-1}$

c = 0.9931

Measurement process

Characterised parameter

dependence of sensitivity to ambient temperature

Measurement function $S(T) = S_0 \cdot (a \cdot T^2 + b \cdot T + c)$

with S(T) sensitivity in $\left[V/(W/m^2)\right]$ at an instrument body temperature

T, S_0 sensitivity at 20 °C instrument body temperature, T the instrument body temperature in [°C], a, b and c the temperature

coefficients determined from a second order polynomial fit

Measurement equipment

Hukseflux Temperature Response Characterisation

Conformity assessment

Definition of measurand*

Temperature response is the remaining percentage deviation in

sensitivity due to change in ambient temperature within a temperature

interval after the temperature coefficients are applied

Temperature interval

-30 to +50 °C

Acceptance interval

Hukseflux specifies a limit on the temperature response for a

SR30-D1 of \pm 0.4 %

Conclusion

Conformity verified

Table 0.3 temperature dependence test result

TEMPERATURE DEPENDENCE TEST							
T [°C]	-30	-10	10	30	50		
remaining deviation	+0.00 %	+0.01 %	-0.04 %	+0.04 %	-0.01 %		

Person performing characterisation:

Date:

H.E. Brouwer

^{*} These temperature coefficients are applied internally in the instrument

^{*} This is an adaptation of the definition in ISO 9060, which specifies a limit on the temperature response for a secondary standard pyranometer of 2 % within a temperature interval of 50 K.



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Tilt sensor characterisation

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Product type

pyranometer

Measurand

hemispherical solar radiation

Classification secondary standard (ISO 9060), high quality (WMO-No. 8)

Characterisation result*	x-axis	y-axis	z-axis
gain	1.0042	0.9943	0.9985
offset	-71	32	0
temperature coefficient a ₀	-0.2115 x 10 ⁻¹²	-1.3030 x 10 ⁻¹²	0.0169 x 10 ⁻¹²
temperature coefficient a ₁	0.3552	1.2346	1.8708
temperature coefficient a ₂	-0.8732 x 10 ⁻²	0.2671 x 10 ⁻²	-0.1996 x 10 ⁻²
temperature coefficient a ₃	-0.4023 x 10 ⁻⁴	1.1757 x 10 ⁻⁴	0.0032 x 10 ⁻⁴

^{*} These gains, offsets and temperature coefficients are applied internally in the instrument

Measurement process

Characterised parameters Measurement equation tilt sensor gains and offsets

 $\theta = 360/2\pi \cdot atan((x^2 + y^2)^{1/2}/z)$ x,y,z = gain_{x,y,z}·raw_{x,y,z} + offset_{x,y,z} + d_{x,y,z}(T)

 $d_{x,y,z}(T) = a_{0x,0y,0z} + a_{1x,1y,1z} \cdot T + a_{2x,2y,2z} \cdot T^2 + a_{3x,3y,3z} \cdot T^3$

with θ the sensor tilt angle with respect to the horizontal in [°], atan the arctangent function, x, y and z the corrected accelerometer counts, gain_{x,y,z} the tilt sensor gains, raw_{x,y,z} the raw accelerometer counts, offset_{x,y,z} the tilt sensor offsets, d_{x,y,z}(T) the correction for temperature dependence of the tilt measurement at an instrument body temperature T, a₀, a₁, a₂ and a₃ the temperature coefficients determined from a third order polynomial fit. Labels x, y and z refer to

the three accelerometer axes.

Measurement process Alignment with the I

Alignment with the bubble level is attained in horizontal position by

introducing gains and offsets.

Gains and offsets are determined in horizontal position and at a tilt angle of 90 $^{\circ}$. Temperature dependence of the tilt measurement is determined at a tilt angle of 90 $^{\circ}$ between -30 and + 50 $^{\circ}$ C.

Measurement method Hukseflux Tilt Sensor Characterisation

Conformity assessment

Description of assessment
The tilt measurement uncertainty is verified in horizontal position and

at a tilt angle of 90 °

Acceptance interval

The tilt measurement uncertainty is specified at \pm 1° (0 to 90°)

Conclusion Conformity verified

Person performing tilt sensor characterisation:

Date:

G.J. Halve