SIO Shipboard Meteorological Sensor Specifications

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1. General information

SIO vessels are equiped with the following Meteorological sensors:

Air Temperature
Barometric Pressure
Relative Humidity/Air Temperature
Wind Speed/Direction
Long Wave Radiation
Short Wave Radiation
Surface PAR
Precipitation

Underway system sensors are:

Sea Surface Temperature	
Thermosalinograph	
Oxygen	
Fluorometer	
Flowmeter	

Data from the above sensors are acquired, timestamped and stored by the MET acquisition computer along with data from the ship's GPS, Gyrocompass, Echosounder and, if available, the speed log.

The meteorological sensors used on SIO vessels are unmodified from the original manufacturers specifications with the exception of the installation of a common type of connector. This allows the sensors to be interchangeable between all SIO ships so that the sensors can be easily replaced and periodically rotated between ship and shore for maintenance/calibrations.

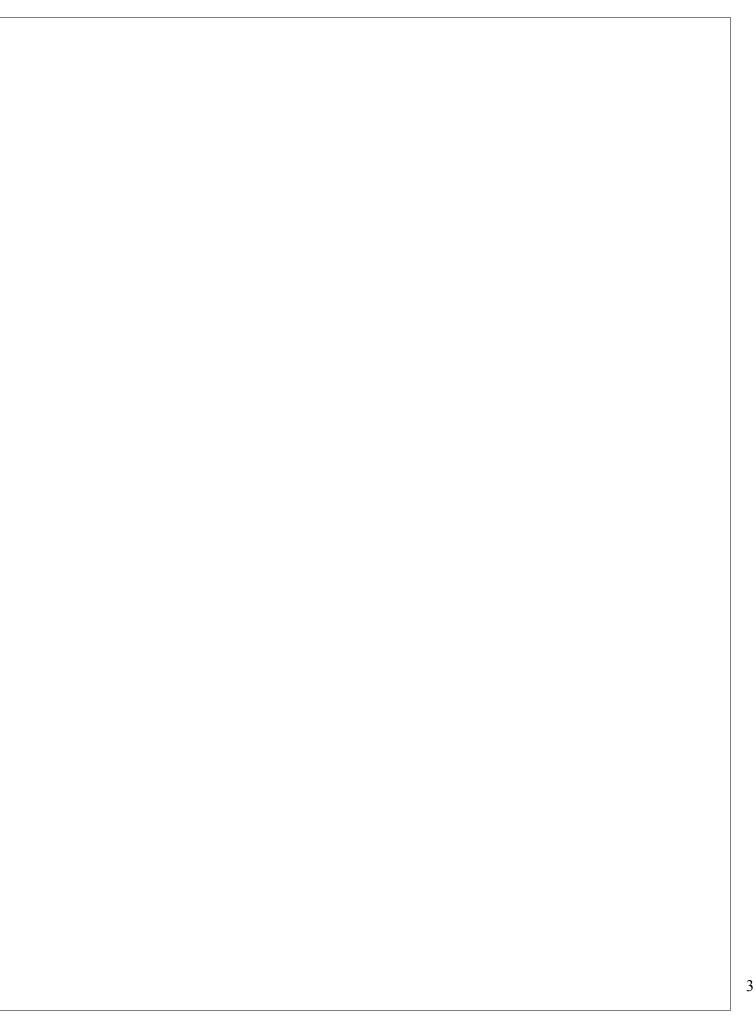
Depending on the make and model of the sensor the data output may be RS485, RS232 or analog signal out.

The mast junction box that is installed on each ship is designed to accommodate sensors of different output types. There are also provisions for expansion to support specific science expedition requirements. MET Sensors are calibrated at a 8-12 months periodicity. Sensor accuracy and calibration specifications are listed in section 2.

Atmospheric sensors plug into a MET Sensor junction box (SEG-8) that utilizes analog to RS485 converters as well as RS232 to RS485 converters. It can accommodate the following number of sensor types.

RS485 inputs RS232 inputs Analog voltage inputs Analog 4-20ma inputs

Air Temperature and Humidity sensors are installed in a multi-plate radiation shield. The Barometer utilizes a static pressure head



2. Meteorological Sensors used on SIO vessels

Type	MFG	Model	Range	Accuracy	Output
Air	RM Young	41342LC			4-20 ma
Temperature					
Air RM Young 41342VC -50.0 to +50.0 C		-50.0 to +50.0 C	+/- 0.3 Deg C	0 – 1 Volts	
Temperature					
Precipitation	RM Young	50202	0-50 mm	+/- 1.0 mm	0 - 5 Volts
Wind	RM Young	05103	Dir 0-360 Deg	+/- 3.0 Deg	Voltage Out
			Spd 0-60 m/s	+/- 0.3 m/s	Pulse Count
Wind	Vaisala	WS425	Dir 0-360 Deg	+/- 2.0 Deg	RS232
			Spd 0-65 m/s	+/- 0.14 m/s	
Wind	RM Young	85000	Dir 0-360 Deg	+/- 2.0 Deg	RS232
		or	Spd 0-70 m/s	+/- 0.1 m/s	
		85106			
Humidity/Temp	Vaisala	HMP45A	RH 0-100%	+/-2.0%	0 – 1 VDC
			Tmp -40 to +60 C	+/- 0.2 Deg C	0 – 1 VDC
Humidity/Temp	RM Young	41382VC	RH 0-100%	+/-2.0%	0 – 1 VDC
			Tmp -50 to +50 C	+/- 0.3 Deg C	0 – 1 VDC
Humidity/Temp	Vaisala	HMP155	RH 0-100%	+/-2.0%	0 – 1 VDC
			Tmp -40 to +60 C	+/- 0.2 Deg C	0 – 1 VDC
			r · · · · · ·		or RS232
Barometer	RM Young	61302V	500-1100mb	+/-0.2mb	0-5V or
				, , , , , , , , , , , , , , , , , , , ,	RS232
Barometer	Vaisala	PTB101C	900-1100 mb	+/- 0.3 mb	0 - 2.5VDC
Radiometer	Eppley	PIR	3.5-50 um	+/- 1%	0 - 10 mv
Long Wave		Pyrgeometer	4 uv/W/M2	Linearity	
			Response Time 2sec		
Radiometer	Eppley	PSP	285-2800nm	+/- 0.5%	0 – 100mv
Short Wave		Pyranometer	9 uv/W/M2	Linearity	
			Response Time 1sec		
Radiometer	Eppley	8-48	285-2800nm	+/- 1%	0 – 100mv
Black&White			10 uv/W/M2	Linearity	
Radiometer	Zipp&Zonen	CM21	305-2800nm	+/- 0.25%	0 – 100mv
Short Wave		Pyranometer	7-25uv/W/M2	Linearity	
			Response Time 5sec		
Radiometer	Zipp&Zonen	CG4	4.5-42 um	+/- 1%	0 - 10 mv
Long Wave		Pyrgeometer	10 uv/W/M2	Linearity	
			Response Time 25sec		
Surface PAR	Biospherical	QSR-240P	400-700nm	Not Specified	0 - 5VDC
			1.4e-5uE/(cm2-sec) to		
			0.5uE/(cm2-sec)		
Surface PAR	Biospherical	QSR-2200	400-700nm	Not Specified	0 - 5VDC
			1.4e-5uE/(cm2-sec) to		
			` ′		
			0.5uE/(cm2-sec)		

All sensor tolerance and accuracy values listed in this section are taken from the manufacturers specification sheets. They are derived under laboratory conditions and do not necessarily indicate the accuracies that may be expected in actual shipboard installations. They do not take into account the effects of ship roll, pitch, sway, solar radiation, shipboard structural interference and thermal radiation effects of the ship itself. These effects will vary from ship to ship. Placing the sensors forward on the ship and as high as possible minimizes some of the ship structural radiation effects. This is the case on R/V Revelle and R/V Melville, each has a bow, mounted MET mast.

Underway Uncontaminated Seawater System

TYPE	MFG	Model	Range	Accuracy	Output
Thermosalinograph	Seabird	SBE-45	Temp –5 to +35 C	+/- 0.002 Deg C	RS232
			Cond 0 to 70 mS/cm	+/- 0.003 mS/cm	
Fluorometer	Wetlabs	WetStar	0.03 to 75 ug/l	Not Specified	0 - 5VDC
Fluorometer	Seapoint	SCF	Various gain settings	Not Specified	0 - 5VDC
			Usually - 0 to 50 ug/l		
Oxygen	Seabird	SBE-43	120% surf saturation	2%	0 - 5VDC
Hull mounted	STS	SEG-14	Temp –2 to +35 C	+/- 0.1 Deg C	RS232
Sea Surf Temp					
Flow Meter	Signet	515-PO	0-80 GPM	+/- 1.0% FS	Pulse
					Count
Flow Meter	FLO-CAT	C-ES45-	0.27 – 18.9 LPM	+/- 1.0% FS	Pulse
		B002			Count
Flow Meter	FLO-CAT	C-ES45-	0.38 – 37.9 LPM	+/- 1.0% FS	Pulse
		B003			Count

3. R/V New Horizon

Upper bridge (Forward) 36' above mean water line:

Air Temperature		
Barometer		
Humidity/Air Temperature		
Long Wave Radiation		
Short Wave Radiation		
Surface PAR		

Upper Bridge (Port side)

Wind Speed/Direction

Precipitation

Upper Bridge (Starboard side)

Wind Speed/direction

Aft Lab (Port Side):

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Thermosalinograph	
Flow Meter	
*Fluorometer	
*Oxygen Sensor	

^{*}Installed upon request prior to cruise

Uncontaminated Seawater feeds a vortex debubbler. The output of the debubbler supplies the flo-thru system.

Machine shop Compartment (Starboard side)

SEG-14 Sea Surface Temperature

Shipboard Data feeds to the MET system:

Gl	PS Units - Furuno GP90
Sh	ip's Gyro Sperry
Не	eading - Ashtech ADU2
W	ater Depth – Knudsen 3260
Se	lected Winch – Meters of wire, Speed MPM, tension
\mathbf{C}	TD – CTD Depth, Descent rate, Altimeter

4. R/V Sproul

Upper bridge (Port side) 33' above mean water line:

Air Temperature	
Barometer	
Humidity/Air Temperature	
Precipitation	
Wind	
Long Wave Radiation	
Short Wave Radiation	

Main Lab (starboard side):

*Thermosalinograph

*Fluorometer

Surface PAR

*Oxygen

*Flow

Transducer void

SEG-14 Sea Surface Temperature

Shipboard Data feeds to the MET system:

GPS - Furuno (GP90, GP150
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Ship's Gyro Sperry

Heading - Ashtech ADU2

Water Depth - Knudsen BR320

Selected Winch - Meters of wire, Speed MPM, tension

CTD - CTD Depth, Descent rate, Altimeter

^{*}Installed upon request prior to cruise

5. R/V Revelle

Forward MET Mast - Met platform - 56'above Mean Water Line.

Air Temperature
Barometer
Humidity/Air Temperature
Precipitation
Wind

Forward MET Mast – Top of Met mast - 68' above mean water line

Long Wave Radiation	
Short Wave Radiation	
Surface PAR	

Flow-Thru System – Hydro Lab

Thermosalinograph	
Fluorometer	
Oxygen	
Flow	

Uncontaminated Seawater feeds a vortex debubbler. The output of the debubbler supplies the flo-thru system.

Bow Thruster Room

Thermosalinograph	
Flow Meter	

The Thermosalinograph is located about 7' from the seawater intake.

An LCD panel in this area provides a local readout for Sea Surface Temperature, Salinity and water flow in the uncontaminated seawater supply.

Shipboard Data feeds to the MET system:

GPS - Furuno GP90, GP150, Trimble SPS351, Ashtech, Hydrins, Phins		
Phins or Hydrins INS Gyro, Pitch, Roll, Heave		
Heading - Ashtech ADU2		
Water Depth – Simrad EM-122		
Water Depth – Knudsen 3260		
Gravimeter BGM3		
Magnetometer – Geometrics SeaSpy		
Hydro Winch – Meters of wire, Speed MPM, tension		
Trawl Winch Meters of wire, Speed MPM, tension		
CTD – CTD Depth, Descent rate, Altimeter		

6. R/V Melville

Forward MET mast on bow - 55' above the mean water line:

Air Temperature
Barometer
Humidity/Air Temperature
Precipitation
Wind
Long Wave Radiation
Short Wave Radiation
Surface PAR

Flow-Thru System – Bioanalytical Lab

Thermosalinograph	
Fluorometer	
Oxygen	
Flow	
Water Temperature	

Uncontaminated Seawater feeds a vortex debubbler. The output of the debubbler supplies the flo-thru system.

Bow Chamber:

Flow Meter
SEG-14 Sea Surface Temperature Sensors

Shipboard Data feeds to the MET system:

GPS - Furuno GP90, GP150, Coda F185, Ashtech		
Meridian Gyro		
F185 INS Gyro, Pitch, Roll, Heave		
Heading - Ashtech ADU5		
Water Depth – Simrad EM-122		
Water Depth – Knudsen 3260		
Gravimeter BGM3		
Magnetometer – Geometrics SeaSpy		
Selected Winch – Meters of wire, Speed MPM, tension		
CTD – CTD Depth, Descent rate, Altimeter		